

Asset Pricing
under Asym.
Information

Kyle (1985)

Classification
of Models

Static

Dynamic

Dynamic
Programming
Dynamic Kyle

Extensions

Asset Pricing under Asymmetric Information Strategic Market Order Models

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A Classification of Market Microstructure Models

Classification of Models

Static

Dynamic

Dynamic Programming
Dynamic Kyle

Extensions

- simultaneous submission of demand schedules
 - competitive rational expectation models
 - strategic share auctions
- sequential move models
 - screening models in which the market maker submits a supply schedule first
 - static
 - ◊ uniform price setting
 - ◊ limit order book analysis
 - dynamic sequential trade models with multiple trading rounds
 - strategic market order models where the market maker sets prices ex-post

Strategic Market Order Models - Overview

Classification of Models

Static

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Extensions

- Kyle (1985) model
 - static version
 - dynamic version (in discrete time)
 - Refresher in Dynamic Programming
 - continuous time version (Back 1992)
- Multi-insider Kyle (1985) version
- Other strategic market order models

Kyle 1985 Model

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Extensions

- Model Setup

- asset return $v \sim \mathcal{N}(p_0, \Sigma_0)$
- Agents (risk neutral)
 - Insider who knows v and submit market order of size x
 - Noise trader who submit market orders of exogenous aggregate size $u \sim \mathcal{N}(0, \sigma_u^2)$
 - Market maker sets competitive price after observing **net** order flow $X = x + u$
- Timing (order of moves)
 - Stage 1: Insider & liquidity traders submit market orders
 - Stage 2: Market Maker sets the execution price
- Repeated trading in dynamic version

Kyle 1985 Model — Static Version

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Single informed trader	(Competitive) Market Maker
0) <u>Information</u> $v :=$ asset's payoff	0) <u>Information</u> $X = x + u$ batch net order flow
1) <u>Conjecture (price-rule)</u> $p = \mu + \lambda(x + u)$	1) <u>Conjecture (insider trading rule)</u> $x = \alpha + \beta v$
2) <u>No Updating</u>	2) <u>Updating</u> $E[v x + u]$
3) <u>Optimal Demand</u> $\max_x E[(v - p) v]x$ $\max_x E[v - \mu - \lambda x v]x$ FOC: $x = -\frac{\mu}{2\lambda} + \frac{1}{2\lambda}v$ SOC: $\lambda > 0$	3) <u>Price Setting Rule</u> $p = E[v x + u]$ $p = E[v] + \frac{\text{Cov}[v, x+u]}{\text{Var}[x+u]} \{x + u - E[x + u]\}$ $p = p_0 + \frac{\beta \Sigma_0}{\beta^2 \Sigma_0 + \sigma_u^2} \{x + u - \alpha + \beta E[v]\}$
4) <u>Correct Beliefs</u> $\alpha = -\frac{\mu}{2\lambda}, \beta = \frac{1}{2\lambda}$	4) <u>Correct Beliefs</u> $\mu = p_0$ Martingale, $\lambda = \frac{\beta \Sigma_0}{\beta^2 \Sigma_0 + \sigma_u^2}$

Kyle 1985 Model — Static Version

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- solve for unknown coefficients
 - 4 unknown Greeks
 - 4 equations
- $\lambda = \frac{1}{2} \sqrt{\frac{\Sigma_0}{\sigma_u^2}}$
 - λ (illiquidity) decreases with noise trading, σ_u^2
 - Σ_0 reflect info advantage of insider

Dynamic Programming - A Refresher

- The Problem:

max for several periods $t = 1, \dots, T$ (discrete time)

$$\max_{u_t} E_t \left[\sum_{s=1}^T v_s (\tilde{x}_s, u_s) \right] \quad \forall t \Rightarrow \text{(sequential rationality)}$$

under the following law of motion

$$\tilde{x}_{t+1} = f_t (\tilde{x}_t, u_t, \varepsilon_t)$$

\tilde{x}_t : vector of state variables (sufficient state space)

u_t : vector of control variables

ε_t : vector of random shocks

- Method

- Backward Induction
- Dynamic Programming

Dynamic Programming - A Refresher

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- Define Value Function

$$V_t(x_t) := E_t \left[\sum_{s=t}^T v_s(\tilde{x}_s, u_s^*) \right]$$

↑
optimal values

- ⇒ Bellman Equation

$$\max_{u_t} E_t [v_t(x_t, u_t) + V_{t+1}(x_{t+1})]$$

- Start at final date T

$$V_{T+1}(\cdot) := 0$$

⇒ in $t = T$

$$\max_{u_T} E_T [v_T(x_T, u_T)]$$

$$\stackrel{\text{FOC}}{\Rightarrow} u_T^* = g_T(x_T)$$

$$\Rightarrow V_T(x_T) = E_T [v_T(x_T, u_T^*)]$$

Dynamic Programming - A Refresher

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- at date $T - 1$

$$\max_{u_{T-1}, u_T} E_{T-1} \left[\sum_{s=T-1}^T v_s (\tilde{x}_s, u_s) \right]$$

given $V_T(x_T)$

$$\Leftrightarrow \max_{u_{T-1}} E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}) + V_T(x_T)]$$

given law of motion

\Leftrightarrow

$$\begin{aligned} & \max_{u_{T-1}} E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}) + V_T(f_{T-1}(x_{T-1}, u_{T-1}, \tilde{\varepsilon}_{T-1}))] \\ & \Rightarrow u_{T-1}^* = g_{T-1}(x_{T-1}) \\ & \Rightarrow V_{T-1} = \end{aligned}$$
$$E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}^*) + V_T(f_{T-1}(x_{T-1}, u_{T-1}^*, \tilde{\varepsilon}_{T-1}))]$$

- and so on for date $T - 2$ etc. (and if they didn't die in the uncertainties they are still solving ...)
- This process is quite time consuming.

Dynamic Programming - A Refresher

Alternative way:

- **Step 1:** “Guess” the general form of the value function

$$V_{t+1}(x_{t+1}) = \underbrace{H_{t+1}(x_{t+1})}_{\text{e.g. } H_{t+1}(x_{t+1}) = \alpha_{t+1}x_{t+1}^2}$$

- **Step 2:** Derive optimal level of current control

$$\begin{aligned} & \max_{u_t} E_t [v_t(x_t, u_t) + H_{t+1}(\tilde{x}_{t+1})] \\ & \max_{u_t} E_t [v_t(x_t, u_t) + H_{t+1}(f_t(x_t, u_t, \varepsilon_t))] \\ \Rightarrow \quad & u_t^* = \dots \end{aligned}$$

- **Step 3:** Derive value function and check whether it coincides with general value function

$$\begin{aligned} V_t(x_t) &= E_t [v_t(x_t, u_t^*) + H_{t+1}(f_t(x_t, u_t^*, \tilde{\varepsilon}_t))] \\ &\stackrel{?}{=} H_t(x_t) = \alpha_t x_t^2 \end{aligned}$$

Kyle (1985) — Dynamic Version

Insider

- **Step 1:** Conjectured price setting strategy (pricing rule)

$$\begin{aligned} p_n &= p_{n-1} + \lambda_n \Delta X_n \\ &= p_{n-1} + \lambda_n (\Delta x_n + \Delta u_n) \quad \left(\frac{1}{\lambda_t} \cong \text{Liquidity} \right) \end{aligned}$$

- **Step 2:** 'Guess' Value function for insider's profit pricing rule is linear \rightarrow guess quadratic value function)

$$E[\pi_{n+1} | \underbrace{\tilde{p}_1, \dots, p_n, v}_{\substack{\text{Information set} \\ \text{up to } n}}] = \alpha_n (v - p_n)^2 + \delta_n$$

(expected profit from time $n + 1$ onwards)

$$\pi_n = E_n [\pi_{n+1} + (v - p_n) \Delta x_n^i]$$

Kyle (1985) — Dynamic Version

Insider ctd.

- **Step 3:** Write Bellman Equation

$$\max_{\Delta x_n^i} E \left[(\nu - p_n) \Delta x_n^i + \alpha_n (\nu - p_n)^2 + \delta_n \underbrace{| p_1, \dots, p_{n-1}, \nu}_{I_{n-1}} \right]$$

- **Step 4:** Given insider's beliefs $p_n = p_{n-1} + \lambda_n \Delta X_n$

$$\max_{\Delta x_n^i} E \left[\begin{array}{l} (\nu - p_{n-1} - \lambda_n \Delta x_n^i - \lambda_n \Delta u_n) \Delta x_n^i \\ + \alpha_n (\nu - p_{n-1} - \lambda_n \Delta x_n^i - \lambda_n u_n)^2 + \delta_n \end{array} \middle| I_n \right]$$

Take expectations

$$\max_{\Delta x_n^i} \left[\begin{array}{l} (\nu - p_{n-1} - \lambda_n \Delta x_n^i) \Delta x_n^i + \alpha_n (\underbrace{\nu - p_{n-1}}_{\text{state variable}} - \lambda_n \underbrace{\Delta x_n^i}_{\text{control}})^2 \\ + \delta_n + \alpha_n \lambda_n^2 \underbrace{\sigma_u^2}_{u \Rightarrow p_n \text{ noisy}} \Delta t_n \end{array} \right]$$

Kyle (1985) — Dynamic Version

Insider ctd.

- **Step 5:** maximize

$$\text{FOC: } (\nu - p_{n-1}) - 2\lambda_n \Delta x_n^i - 2\alpha_n \lambda_n (\nu - p_{n-1}) + 2\alpha_n \lambda_n^2 \Delta x_n^i = 0$$

$$\Delta x_n^i = \underbrace{\frac{1 - 2\alpha_n \lambda_n}{2\lambda_n (1 - \alpha_n \lambda_n)}}_{:= \beta_n \Delta t_n} (\nu - p_{n-1})$$

$$\text{SOC: } \lambda_n (1 - \alpha_n \lambda_n) > 0$$

- **Step 6:** Check whether ‘guessed’ value fcn is correct

$$E[\pi | I_{n-1}] = \max_{\Delta x_n^i} E \left[(\nu - p_n) \Delta x_n^i + \alpha_n (\tilde{\nu} - \tilde{p}_n)^2 + \delta_n | I_{n-1} \right]$$

$$= \alpha_{n-1} (\nu - p_{n-1})^2 + \delta_{n-1}, \text{ where}$$

$$\alpha_{n-1} = \frac{1}{4\lambda_n (1 - \alpha_n \lambda_n)}, \quad \delta_{n-1} = \delta_n + \alpha_n (\lambda_n)^2 \sigma_u^2 \Delta t_n$$

Kyle (1985) — Dynamic Version

Market Maker (Filtering Problem)

- **Step 1:** MM's belief about insider's strategy

$$\Delta x_n^i = \beta_n \Delta t_n (v - p_{n-1})$$

$$\Delta X_n = \beta_n \Delta t_n (v - p_{n-1}) + \underbrace{\Delta u_n}_{Var[\Delta u_n] = \sigma_u^2 \Delta t_n}$$

- **Step 2:** MM's filtering problem

By definition:

$$p_{n-1} : = E[v | \Delta X_1, \dots, \Delta X_{n-1}]$$

$$\Sigma_{n-1} : = Var[v | \Delta X_1, \dots, \Delta X_{n-1}]$$

$$E[\Delta X_n | \Delta X_1, \dots, \Delta X_{n-1}] = \beta_n \Delta t_n E[(v - p_{n-1}) + \Delta u_n | \dots]$$

$$Var[\Delta X_n | \dots] = (\beta_n \Delta t_n)^2 \Sigma_{n-1} + \sigma_u^2 \Delta t_n$$

$$Cov[v, \Delta X_n | \dots] = E[v(\beta_n \Delta t_n (v - p_{n-1}) + \Delta u_n)]$$

$$= \beta_n \Delta t_n \Sigma_{n-1}$$

Kyle (1985) — Dynamic Version

Now we have all ingredients for the **Projection Theorem**

$$p_n = p_{n-1} + \underbrace{\frac{\beta_n \Delta t_n \Sigma_{n-1}}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2}}_{:= \lambda_n} \Delta X_n$$

$$\begin{aligned} \sum_n &= V[v | \dots \Delta X_n] = \Sigma_{n-1} - \frac{(\beta_n \Delta t_n)^2 \Sigma_{n-1}^2}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2} \\ &= \frac{\sigma_u^2 \Sigma_{n-1}}{(\beta_n)^2 \Delta t_n \Sigma_{n-1} + \sigma_u^2} \end{aligned}$$

\Rightarrow

$$\lambda_n = \frac{\beta_n \Delta t_n \Sigma_{n-1}}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2}$$

$$\sum_n = (1 - \lambda_n \beta_n \Delta t_n) \Sigma_{n-1} = \frac{\sigma_u^2 \lambda_n}{\beta_n}$$

$$\Rightarrow \lambda_n = \beta_n \Sigma_n / \sigma_u^2$$

Kyle (1985) — Dynamic Version

- **Step 3:** Equate coefficients $\alpha_n, \beta_n, \delta_n, \sum_n$

$$\left. \begin{array}{l} \beta_n \Delta t_n = \frac{1 - 2\alpha_n \lambda_n}{2\lambda_n(1 - \alpha_n \lambda_n)} \\ \alpha_{n-1} = \frac{1}{4\lambda_n(1 - \alpha_n \lambda_n)} \\ \delta_{n-1} = \delta_n + \alpha_n \lambda_n^2 \sigma_u^2 \Delta t_n \\ \sum_n = \sigma_u^2 \sum_{n-1} \\ \lambda_n = \dots \end{array} \right\}$$

Solve recursive system of equations.

- Interpretation of Equilibrium
 - restrain from aggressive trading
 - price impact in current trading round
 - price impact in all future trading rounds
 - ...

Generalizations of Kyle (1985)

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Extensions

- Multiple Insiders
 - all have same information
 - all hold different information
 - information is correlated
⇒ see Foster & Viswanathan, JF 51, 1437-1478
- Risk averse insiders
 - CARA utility
 - etc. etc.