

Asset Pricing under Asymmetric Information Rational Expectations Equilibrium

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A Classification of Market Microstructure Models

- simultaneous submission of demand schedules
 - competitive rational expectation models
 - strategic share auctions
- sequential move models
 - screening models in which the market maker submits a supply schedule first
 - static
 - ◇ uniform price setting
 - ◇ limit order book analysis
 - dynamic sequential trade models with multiple trading rounds
 - strategic market order models where the market maker sets prices ex-post

Strategic Market Order Models - Overview

- Kyle (1985) model
 - static version
 - dynamic version (in discrete time)
 - Refresher in Dynamic Programming
 - continuous time version (Back 1992)
- Multi-insider Kyle (1985) version
- Other strategic market order models

Kyle 1985 Model

- Model Setup
 - asset return $v \sim \mathcal{N}(\mu_0, \Sigma_0)$
 - Agents (risk neutral)
 - Insider who knows v and submit market order of size x
 - Noise trader who submit market orders of exogenous aggregate size $u \sim \mathcal{N}(0, \sigma_u^2)$
 - Market maker sets competitive price after observing **net** order flow $X = x + u$
 - Timing (order of moves)
 - Stage 1: Insider & liquidity traders submit market orders
 - Stage 2: Market Maker sets the execution price
 - Repeated trading in dynamic version

Kyle 1985 Model — Static Version

Single informed trader

0) Information

$v :=$ asset's payoff

1) Conjecture (price-rule)

$$p = \mu + \lambda(x + u)$$

2) No Updating

3) Optimal Demand

$$\max_x E[(v - p)|v]x$$

$$\max_x E[v - \mu - \lambda x|v]x$$

$$\text{FOC: } x = -\frac{\mu}{2\lambda} + \frac{1}{2\lambda}v$$

$$\text{SOC: } \lambda > 0$$

4) Correct Beliefs

$$\alpha = -\frac{\mu}{2\lambda}, \beta = \frac{1}{2\lambda}$$

(Competitive) Market Maker

0) Information

$X = x + u$ batch net order flow

1) Conjecture (insider trading rule)

$$x = \alpha + \beta v$$

2) Updating $E[v|x + u]$

3) Price Setting Rule

$$p = E[v|x + u]$$

$$p = E[v] + \frac{\text{Cov}[v, x+u]}{\text{Var}[x+u]} \{x + u - E[x + u]\}$$

$$p = p_0 + \frac{\beta \Sigma_0}{\beta^2 \Sigma_0 + \sigma_u^2} \{x + u - \alpha + \beta E[v]\}$$

4) Correct Beliefs

$$\mu = p_0 \text{ Martingale, } \lambda = \frac{\beta \Sigma_0}{\beta^2 \Sigma_0 + \sigma_u^2}$$

Kyle 1985 Model — Static Version

- solve for unknown coefficients
 - 4 unknown Greeks
 - 4 equations
- $\lambda = \frac{1}{2} \sqrt{\frac{\Sigma_0}{\sigma_u^2}}$
 - λ (illiquidity) decreases with noise trading, σ_u^2
 - Σ_0 reflect info advantage of insider

Dynamic Programming - A Refresher

- The Problem:
max for several periods $t = 1, \dots, T$ (discrete time)

$$\max_{u_t} E_t \left[\sum_{s=1}^T v_s (\tilde{x}_s, u_s) \right] \quad \forall t \Rightarrow (\text{sequential rationality})$$

under the following law of motion

$$\tilde{x}_{t+1} = f_t(\tilde{x}_t, u_t, \tilde{\varepsilon}_t)$$

\tilde{x}_t : vector of state variables (sufficient state space)

u_t : vector of control variables

ε_t : vector of random shocks

- Method
 - Backward Induction
 - Dynamic Programming

Dynamic Programming - A Refresher

- Define Value Function

$$V_t(x_t) := E_t \left[\sum_{s=t}^T v_s(\tilde{x}_s, \underset{\substack{\uparrow \\ \text{optimal values}}}{u_s^*}} \right]$$

- \Rightarrow Bellman Equation

$$\max_{u_t} E_t [v_t(x_t, u_t) + V_{t+1}(x_{t+1})]$$

- Start at final date T

$$V_{T+1}(\cdot) := 0$$

\Rightarrow in $t = T$

$$\max_{u_T} E_T [v_T(x_T, u_T)]$$

$$\stackrel{\text{FOC}}{\Rightarrow} u_T^* = g_T(x_T)$$

$$\Rightarrow V_T(x_T) = E_T [v_T(x_T, u_T^*)]$$

Dynamic Programming - A Refresher

- at **date** $T - 1$

$$\max_{u_{T-1}, u_T} E_{T-1} \left[\sum_{s=T-1}^T v_s (\tilde{x}_s, u_s) \right]$$

given $V_T(x_T)$

$$\Leftrightarrow \max_{u_{T-1}} E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}) + V_T(x_T)]$$

given law of motion

$$\Leftrightarrow \max_{u_{T-1}} E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}) + V_T(f_{T-1}(x_{T-1}, u_{T-1}, \tilde{\varepsilon}_{T-1}))]$$

$$\Rightarrow u_{T-1}^* = g_{T-1}(x_{T-1})$$

$$\Rightarrow V_{T-1} =$$

$$E_{T-1} [v_{T-1}(x_{T-1}, u_{T-1}^*) + V_T(f_{T-1}(x_{T-1}, u_{T-1}^*, \tilde{\varepsilon}_{T-1}))]$$

- and so on for **date** $T - 2$ etc. (and if they didn't die in the uncertainties they are still solving ...)
- This process is quite time consuming.

Dynamic Programming - A Refresher

Alternative way:

- **Step 1:** "Guess" the general form of the value function

$$V_{t+1}(x_{t+1}) = \underbrace{H_{t+1}(x_{t+1})}_{\text{e.g. } H_{t+1}(x_{t+1}) = \alpha_{t+1}x_{t+1}^2}$$

- **Step 2:** Derive optimal level of current control

$$\begin{aligned} \max_{u_t} E_t [v_t(x_t, u_t) + H_{t+1}(\tilde{x}_{t+1})] \\ \max_{u_t} E_t [v_t(x_t, u_t) + H_{t+1}(f_t(x_t, u_t, \varepsilon_t))] \\ \Rightarrow u_t^* = \dots \end{aligned}$$

- **Step 3:** Derive value function and check whether it coincides with general value function

$$\begin{aligned} V_t(x_t) &= E_t [v_t(x_t, u_t^*) + H_{t+1}(f_t(x_t, u_t^*, \tilde{\varepsilon}_t))] \\ \stackrel{?}{=} H_t(x_t) &= \alpha_t x_t^2 \end{aligned}$$

Kyle (1985) — Dynamic Version

Insider

- **Step 1:** Conjectured price setting strategy (pricing rule)

$$\begin{aligned} p_n &= p_{n-1} + \lambda_n \Delta X_n \\ &= p_{n-1} + \lambda_n (\Delta x_n + \Delta u_n) \quad \left(\frac{1}{\lambda_t} \cong \text{Liquidity} \right) \end{aligned}$$

- **Step 2:** 'Guess' Value function for insider's profit pricing rule is linear \rightarrow guess quadratic value function)

$$E[\pi_{n+1} | \underbrace{\tilde{p}_1, \dots, p_n, v}_{\text{Information set up to } n}] = \alpha_n (v - p_n)^2 + \delta_n$$

(expected profit from time $n + 1$ onwards)

$$\pi_n = E_n [\pi_{n+1} + (v - p_n) \Delta x_n^i]$$

Kyle (1985) — Dynamic Version

Insider ctd.

- **Step 3:** Write Bellman Equation

$$\max_{\Delta x_n^i} E \left[(v - p_n) \Delta x_n^i + \alpha_n (v - p_n)^2 + \delta_n \underbrace{|p_1, \dots, p_{n-1}, v}_{I_{n-1}} \right]$$

- **Step 4:** Given insider's beliefs $p_n = p_{n-1} + \lambda_n \Delta X_n$

$$\max_{\Delta x_n^i} E \left[(v - p_{n-1} - \lambda_n \Delta x_n^i - \lambda_n \Delta u_n) \Delta x_n^i + \alpha_n (v - p_{n-1} - \lambda_n \Delta x_n^i - \lambda_n \Delta u_n)^2 + \delta_n \mid I_n \right]$$

Take expectations

$$\max_{\Delta x_n^i} \left[(v - p_{n-1} - \lambda_n \Delta x_n^i) \Delta x_n^i + \alpha_n \underbrace{(v - p_{n-1} - \lambda_n \Delta x_n^i)^2}_{\text{state variable}} + \delta_n + \alpha_n \lambda_n^2 \underbrace{\sigma_u^2}_{\text{control}} \Delta t_n \right]$$

$u \Rightarrow p_n \text{ noisy}$

Kyle (1985) — Dynamic Version

Insider ctd.

- **Step 5:** maximize

$$\text{FOC: } (v - p_{n-1}) - 2\lambda_n \Delta x_n^i - 2\alpha_n \lambda_n (v - p_{n-1}) + 2\alpha_n \lambda_n^2 \Delta x_n^i = 0$$

$$\Delta x_n^i = \frac{1 - 2\alpha_n \lambda_n}{\underbrace{2\lambda_n (1 - \alpha_n \lambda_n)}_{:= \beta_n \Delta t_n}} (v - p_{n-1})$$

$$\text{SOC: } \lambda_n (1 - \alpha_n \lambda_n) > 0$$

- **Step 6:** Check whether 'guessed' value fcn is correct

$$E[\pi | I_{n-1}] = \max_{\Delta x_n^i} E \left[(v - p_n) \Delta x_n^i + \alpha_n (\tilde{v} - \tilde{p}_n)^2 + \delta_n | I_{n-1} \right]$$

$$= \alpha_{n-1} (v - p_{n-1})^2 + \delta_{n-1}, \text{ where}$$

$$\alpha_{n-1} = \frac{1}{4\lambda_n (1 - \alpha_n \lambda_n)}, \quad \delta_{n-1} = \delta_n + \alpha_n (\lambda_n)^2 \sigma_u^2 \Delta t_n$$

Kyle (1985) — Dynamic Version

Market Maker (Filtering Problem)

- **Step 1:** MM's belief about insider's strategy

$$\Delta x_n^i = \beta_n \Delta t_n (v - p_{n-1})$$

$$\Delta X_n = \beta_n \Delta t_n (v - p_{n-1}) + \underbrace{\Delta u_n}_{\text{Var}[\Delta u_n] = \sigma_u^2 \Delta t_n}$$

- **Step 2:** MM's filtering problem

By definition:

$$p_{n-1} : = E [v | \Delta X_1, \dots, \Delta X_{n-1}]$$

$$\Sigma_{n-1} : = \text{Var} [v | \Delta X_1, \dots, \Delta X_{n-1}]$$

$$E [\Delta X_n | \Delta X_1, \dots, \Delta X_{n-1}] = \beta_n \Delta t_n E [(v - p_{n-1}) + \Delta u_n | \dots]$$

$$\text{Var} [\Delta X_n | \dots] = (\beta_n \Delta t_n)^2 \Sigma_{n-1} + \sigma_u^2 \Delta t_n$$

$$\begin{aligned} \text{Cov} [v, \Delta X_n | \dots] &= E [v (\beta_n \Delta t_n (v - p_{n-1}) + \Delta u_n) | \dots] \\ &= \beta_n \Delta t_n \Sigma_{n-1} \end{aligned}$$

Kyle (1985) — Dynamic Version

Now we have all ingredients for the **Projection Theorem**

$$p_n = p_{n-1} + \underbrace{\frac{\beta_n \Delta t_n \Sigma_{n-1}}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2}}_{:= \lambda_n} \Delta X_n$$

$$\begin{aligned} \Sigma_n &= V[v | \dots \Delta X_n] = \Sigma_{n-1} - \frac{(\beta_n \Delta t_n)^2 \Sigma_{n-1}^2}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2} \\ &= \frac{\sigma_u^2 \Sigma_{n-1}}{(\beta_n)^2 \Delta t_n \Sigma_{n-1} + \sigma_u^2} \end{aligned}$$

\Rightarrow

$$\lambda_n = \frac{\beta_n \Delta t_n \Sigma_{n-1}}{(\beta_n \Delta t_n)^2 \Sigma_{n-1} + \Delta t \sigma_u^2}$$

$$\Sigma_n = (1 - \lambda_n \beta_n \Delta t_n) \Sigma_{n-1} = \frac{\sigma_u^2 \lambda_n}{\beta_n}$$

$$\Rightarrow \lambda_n = \beta_n \Sigma_n / \sigma_u^2$$

Kyle (1985) — Dynamic Version

- **Step 3:** Equate coefficients $\alpha_n, \beta_n, \delta_n, \Sigma_n$

$$\left. \begin{aligned} \beta_n \Delta t_n &= \frac{1 - 2\alpha_n \lambda_n}{2\lambda_n(1 - \alpha_n \lambda_n)} \\ \alpha_{n-1} &= \frac{1}{4\lambda_n(1 - \alpha_n \lambda_n)} \\ \delta_{n-1} &= \delta_n + \alpha_n \lambda_n^2 \sigma_u^2 \Delta t_n \\ \Sigma_n &= \sigma_u^2 \Sigma_{n-1} \\ \lambda_n &= \dots \end{aligned} \right\} \begin{array}{l} \text{Solve recursive} \\ \text{system of} \\ \text{equations.} \end{array}$$

- Interpretation of Equilibrium
 - restrain from aggressive trading
 - price impact in current trading round
 - price impact in all future trading rounds
 - ...

Generalizations of Kyle (1985)

- Multiple Insiders
 - all have same information
 - all hold different information
 - information is correlated
 - ⇒ see Foster & Viswanathan, JF 51, 1437-1478
- Risk averse insiders
 - CARA utility
- etc. etc.